

# GELI Support for UEFI

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# Disclaimer

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# Background

- ▶ `geli` is a block-level disk encryption scheme for FreeBSD.
- ▶ Support for booting in X86 BIOS mode from `geli` volumes added by Allan Jude.
- ▶ UEFI boot is very different from X86 BIOS.
- ▶ GELI support for UEFI necessary to support modern hardware, UEFI features (secure boot, UEFI variables, etc.)

# UEFI Boot Process

- ▶ UEFI specification provides a number of APIs for device I/O, memory allocation, driver registration, etc.
- ▶ *No* direct access to devices, control over addresses, etc.
- ▶ Firmware looks for EFI System Partition (ESP), loads boot application from standard location
- ▶ UEFI spec calls for minimum 200Mib ESP, can be larger
- ▶ FreeBSD UEFI boot process has two steps
- ▶ `boot1` is a UEFI application installed to ESP, looks for boot partition, loads `loader.efi`
- ▶ `loader.efi` presents the standard FreeBSD boot shell

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# UEFI Benefits and Challenges

- ▶ Benefit: (mostly) free from space constraints, unlike X86 BIOS
- ▶ Challenge: level of abstraction precludes safely passing arbitrary memory from `boot1` to `loader.efi`
- ▶ Challenge: harder to properly implement GELI driver
- ▶ Challenge: split code base between `boot1` and `loader.efi`
- ▶ Benefit: a lot more tools to work with

## Issue: Key Transmission

- ▶ User should only input password once
- ▶ Naïve implementation would require *three* separate times
- ▶ Need to transmit keys from `boot1` to `loader.efi`, then to kernel
- ▶ X86 BIOS pushed password onto loader's stack, then as an environment variable for the kernel
- ▶ UEFI has stronger separation between stages
- ▶ Want to support multiple passwords
- ▶ Hashed passwords better (only incurs one hashing delay)
- ▶ Ideally, provide straightforward migration to hardware key storage mechanisms

## Issue: Split Codebase

- ▶ `loader.efi` uses `libstand` API with UEFI backend
- ▶ `boot1` used completely separate codebase with its own interface
- ▶ Codebases were almost completely independent, significant duplication
- ▶ `boot1` codebase tended towards minimality, difficult to maintain and improve
- ▶ Any change would require two separate implementations with different underlying designs
- ▶ This code duplication hampered both current as well as planned future work



## Issue: GELI Driver Architecture

- ▶ GELI is designed around GEOM, a multi-layered device interface
- ▶ Can support arbitrarily-complex schemes (GPT/GELIs inside GELIs, and so on)
- ▶ Boot loader support is more limited
- ▶ `boot1` would require complete overhaul to support GELI-like structures
- ▶ `loader.efi` has ability to support “one-layer” schemes (GELIs on partitions)

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# Timeline of Work

- ▶ Attempt to refactor boot1
- ▶ First attempt at unifying boot1 and loader.efi codebases (EFIzation)
- ▶ First working GELI driver!
- ▶ Time in code review, use on real hardware
- ▶ ZFS boot environment issues identified, non-trivial changes to HEAD
- ▶ Design revision, simplification, establishment of new branches
- ▶ Key intake buffers go into kernel
- ▶ Full-disk root-on-ZFS under GELI working on real hardware

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# First Refactor of boot1

- ▶ Purpose was to “rough out” a PoC
- ▶ Introduced a “providers” API to compliment boot modules
- ▶ Created even more code duplication, highlighted need to unify codebases
- ▶ Abandoned in favor of unification

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# UEFI Driver Primer

- ▶ `EFI_DRIVER_BINDING` API allows registration of new drivers
- ▶ Drivers have probe/attach functions for `EFI_HANDLES`
- ▶ Can attach various interfaces to an `EFI_HANDLE`
- ▶ Can also create new `EFI_HANDLES` to represent virtual devices
- ▶ New devices will be automatically probed by all registered drivers
- ▶ UEFI spec guarantees GPT/MSDOSFS drivers

## EFIzation Effort

Observation: UEFI provides an API with the same functionality as libstand; use it instead!

- ▶ First effort to unify boot1 and loader.efi
- ▶ boot1 and loader.efi would use EFI\_SIMPLE\_FILE\_SYSTEM interface
- ▶ Produced “shim” drivers: UEFI-to-libstand, libstand-to-UEFI
- ▶ libstand drivers sat under EFI\_SIMPLE\_FILE\_SYSTEM interface
- ▶ boot1 directly utilized EFI\_SIMPLE\_FILE\_SYSTEM to find and load loader.efi
- ▶ loader.efi continued to use libstand interface, which talked through the other shim to UEFI API



# UEFI Drivers

- ▶ GELI was implemented directly as a UEFI driver
- ▶ GELI used `EFI_DRIVER_BINDING` API to register itself as a driver, created new device handles for GELI volumes it detects
- ▶ Benefit: this carries over across the `boot1/loader.efi` boundary
- ▶ `efipart` *mostly* converted to a UEFI driver
- ▶ Issues with `bcache` prevented full conversion

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# Managing Keys in the Loader

- ▶ UEFI driver interface solves one half of the problem raised by the `boot1/loader.efi` gap
- ▶ `EFI_HANDLES` registered in `boot1` are available in `loader.efi`
- ▶ This provides access
- ▶ Still need *keys* to pass into the kernel

# UEFI KMS Interface

- ▶ UEFI defines a key management system (KMS) interface
- ▶ Implemented a simple in-memory key database as a driver which provides this interface.
- ▶ GELI driver attempts to locate a KMS during initialization
- ▶ GELI stores/retrieves keys from its KMS
- ▶ Kernel metadata step also locates the KMS, transfers all keys into the kernel via the `keybuf` interface

## Kernel Key Intake Buffer (keybuf)

- ▶ Provide a better way of getting keys into the kernel
- ▶ Uses kernel metadata functionality to deliver (by default) up to 64 keys, each up to 4096 bits long
- ▶ Keys have a type code indicating their format
- ▶ Picked up by `crypto`, then subsequently available to other drivers for initialization
- ▶ GELI passes in hashed passwords
- ▶ Designed to be extended to work with hardware crypto

# Boot Crypto Framework (boot\_crypto)

- ▶ Inherited code from X86 BIOS implementation, but created a separate codebase
- ▶ X86 BIOS is space-constrained and only supports AES; UEFI is not space-constrained
- ▶ boot\_crypto is designed around a generic algorithm interface with pluggable backends
- ▶ Designed to anticipate overhaul of crypto framework
- ▶ Also designed to support hardware crypto device implementations

## If/When Trustworthy Hardware KMS/Crypto Exists. . .

Thinking ahead to a time when there is a trustworthy hardware KMS implementation was a consideration in this design

- ▶ In-memory KMS detection aborts if it detects another KMS device (this also deals with `boot1` and `loader.efi` both having to attempt to register the in-memory KMS device)
- ▶ GELI should “just work”, as it talks through the KMS and `boot_crypto` interfaces
- ▶ `boot_crypto` would need to add support
- ▶ “Keys” would likely consist of ID numbers for keys stored in KMS
- ▶ `keybuf` interface could easily add another key type for key IDs

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# Benefits of EFIzed Approach

- ▶ `boot1` reduced to a very minimal program, uses same codebase as `loader.efi`
- ▶ Seamless integration with firmware-provided drivers
- ▶ Dropped MSDOSFS driver
- ▶ Provided framework for hot-plugging support (`bcache` got in the way of full implementation)
- ▶ Laid groundwork for exporting driver code to others

## Drawbacks of EFIzed Approach

- ▶ UEFI does a bad job at supporting non-Microsoft systems and interfaces
- ▶ `EFI_SIMPLE_FILE_SYSTEM` interface is designed around MSDOSFS, sits uncomfortably in a VFS interface
- ▶ Difficult to present the same information in boot shell as in current loader
- ▶ ZFS boot environments lost when talking over UEFI interfaces

Personal takeaway: started with moderately positive views on UEFI, ended with moderately negative views.

# Simplified Unification

Eventually, code changes in HEAD broke the patches in non-trivial ways, and the drawbacks of EFIzed approach were becoming clear.

- ▶ Moved `UEFI-to-libstand` shim out to an independent review (still up for review)
- ▶ Dropped `libstand-to-UEFI` shim altogether
- ▶ Refactored `boot1` to use `libstand`
- ▶ Recovered simplicity, information at boot shell, ZFS boot environments
- ▶ Casualty: progress towards hot-pluggable devices at boot time

## Refurbishing Efforts

- ▶ `efipart` had moved away from a static-numbered, array-based storage scheme for device handles (right move)
- ▶ `efipart` had also split up device handles by drive type (also right move)
- ▶ Found an integer overflow bug in `efipart_realstrategy` when attempting to read past the end of a device (caused crash)
- ▶ `efipart` was manually parsing partition tables and using base device handles
- ▶ This didn't work at all with GELI, so had to revert to direct access through partition device handles

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## Kernel gets keybuf Interface

- ▶ `keybuf` patch went into kernel first
- ▶ X86 BIOS GELI support started using `keybuf`
- ▶ Legacy environment variable method still supported, eventually to be phased out
- ▶ *Definitely* the right move to put `keybuf` in first
- ▶ Anyone using a recent kernel can use UEFI GELI without a kernel update

## Testing on QEMU and Real Hardware

- ▶ QEMU testing setup had a large number of GELI disks, including encrypted/unencrypted UFS, ZFS, also an X86 BIOS setup
- ▶ Tested all combinations on QEMU
- ▶ I had also been using a root-on-ZFS laptop with its L2ARC/Intent log stored on GELI volumes since the EFIzed version
- ▶ Finally, converted a laptop over to a full GELI root-on-ZFS setup
- ▶ Works perfectly (except I forgot the `-R` when taking the ZFS snapshots. . . )

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# Plans for GRUB/Coreboot

- ▶ GRUB is (reportedly) the best way to achieve a Coreboot setup
- ▶ Coreboot is arguably a better option (where it's supported)
- ▶ GRUB already supports GELI, but needs to be updated to use the `keybuf` interface
- ▶ Initial conversations with GRUB developers indicates this shouldn't be hard

# My Long-Term Plans

My overall agenda can be described as “OS-level tamper-resilience”

- ▶ Full-disk encryption (GELI)
- ▶ Trust framework and kernel/module signing
- ▶ Active use of coreboot/setup guides
- ▶ Secure suspend/resume
- ▶ Other uses of trust framework